

Novel Burst-mode Control Strategy for Enhanced Light-load Efficiency of DAB Converters

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Abstract—Dual active bridge (DAB) converter is widely used in many applications. Nonetheless, its efficiency degrades significantly under light-load conditions due to the high switching and conduction losses. Since a detailed analysis for burst-mode design has not been presented in the literature the effective burst-mode control for the light-load condition is proposed in this paper. In the proposed burst-mode, the regular duty and the burst duty are optimally coordinated to achieve the zero-voltage-switching (ZVS) condition and the minimum backflow power at the same time. Moreover, DC bias current is effectively eliminated in the proposed burst-mode. Therefore, the switching loss and conduction loss are simultaneously minimized, thus the light-load efficiency is significantly improved. The detailed analysis and design procedure are also presented. The 4 kW DAB converter prototype is built to verify the proposed method and the experiment results show about 2 % of increment in efficiency of the proposed method compared to the conventional burst-mode method.

Index Terms—Dual active bridge converter, burst-mode, optimal backflow- power, efficiency, light-load condition, ZVS condition.

I. INTRODUCTION

The isolated dual-active-bridge (DAB) converter is one of the most popular converters in applications such as solid-state transformers, multi-input converters, and other applications due to its bidirectional and symmetrical structure, zero-voltage-switching (ZVS), and wide voltage gain regulation capabilities [1]–[3]. These features allow it to be used in systems such as energy storage systems and uninterruptible power supplies, which are characterized by continuously fluctuating output voltage conditions from renewable energy sources or batteries and variable loads. These characteristics necessitate high efficiency over a wide range of effective input-output voltage ratios, particularly under light-load conditions.

The single-phase-shift (SPS) control for DAB converters is the simplest modulation method for DAB control strategies used by industry practitioner due to its low cost, simple implementation, and easy design [4]. However, SPS control of DAB increases backflow power under light-loads, generating circulating currents [5], [6]. To overcome this limitation, many modulation controls such as Extended-phase-shift (EPS),

Dual-phase-shift (DPS), and Triple-phase-shift (TPS) have been proposed [7]–[9]. However, the complexity of control strategies with many control variables makes optimal control difficult. Furthermore, if the voltage gain is not unity in light-load conditions, hard switching occurs, resulting in reduced efficiency [10]. Although additional magnetizing inductance is used to achieve full-range ZVS and improve light-load efficiency of the DAB converter, this is not recommended due to increased size, cost, and losses in some sections [11].

To address the two main issues of SPS control under light-load operation of the DAB, burst-mode is widely used. Burst-mode significantly reduces dependent losses such as conduction loss, switching loss, and core loss [12]. Recently, burst-mode has been applied to DAB converters to improve light-load efficiency. The design of burst-mode parameters, such as burst-mode frequency and burst-mode duty cycle, is presented in [13]. Small-signal modeling for burst-mode control is presented in [14]. However, DC bias current occurs at every first cycle of burst-mode operation, which can cause inductor current spikes and over saturation of transformer in conventional burst-mode [15]–[17].

To improve the performance of the burst-mode, the optimal burst-mode control for the light-load condition is proposed in this paper. In the proposed method the optimal duty is adaptively calculated in the burst-mode control to minimize the backflow power while the burst duty is used for regulating the output voltage. Moreover, DC bias current is effectively eliminated in the proposed burst-mode. The advantages of the proposed burst-mode can be listed as follows:

- 1) No additional components are needed for efficiency improvement at light-load condition.
- 2) The ZVS is achieved for entire load range.
- 3) Backflows power is minimized at the light-load condition.
- 4) DC bias current elimination is applied for the burst-mode.
- 5) Mode switching algorithm between the burst-mode and normal-mode is proposed.

This paper is structured as follows: Section II discusses the operation of DAB converter, and Section III presents the proposed burst-mode for DAB converter. The analysis is verified by experiment in Section V. Finally, the results of the study are summarized in Section VI.

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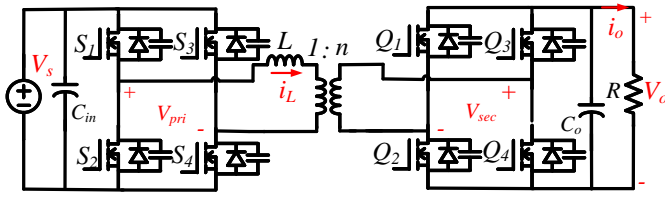


Fig. 1: Isolated DAB converter.

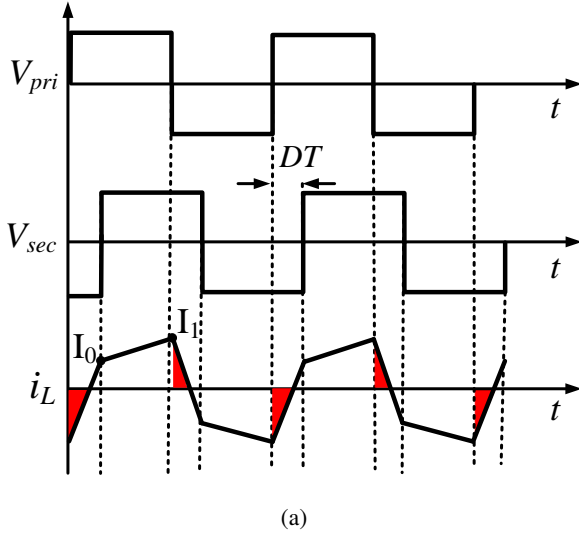


Fig. 2: Key operation waveforms of the DAB converter with SPS.

II. OPERATION OF THE ISOLATED DAB CONVERTER

Fig. 1. shows DAB converter circuit that has two active full-bridge to generate the square wave, a series inductor L to store energy for power transfer, and a transformer with turn ratio $1:n$ to meet the high voltage ratio and provide the galvanic isolation. The key waveform with SPS of DAB converter is shown in Fig. 2, where the currents at the vertices are given by

$$I_0 = \left[V_s + \frac{V_o}{n} (2D - 1) \right] \frac{T_s}{4L} \quad (1)$$

$$I_1 = \left[V_s (2D - 1) + \frac{V_o}{n} \right] \frac{T_s}{4L}.$$

According to the analysis in [6], [10], the voltage gain M and the output power P_o of DAB converter are given by

$$M = \frac{V_o}{nV_s} = \frac{D(1-D)T_s R_L}{2Ln^2} \quad (2)$$

$$P_o = \frac{V_s V_o D(1-D)}{2nf_s L} \quad (3)$$

where D , T_s , and R_L are the regular duty cycle, the switching period, and the load resistance. V_s and V_o are the input voltage and the output voltage of DAB converter. The current causing

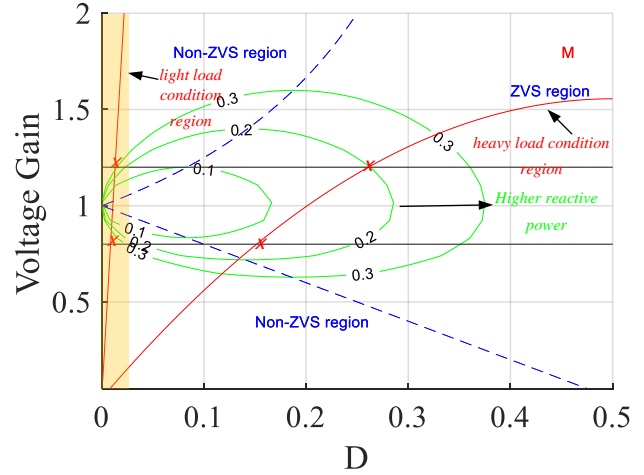


Fig. 3: ZVS condition and backflows power for different voltage gains and load conditions.

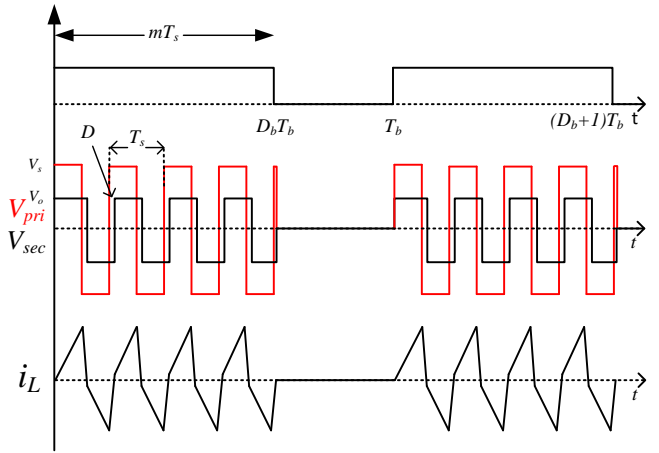


Fig. 4: Burst-mode operation waveform.

backflow power Q of DAB converter are shown in the red area in Fig. 2 and its formula are given by

$$\begin{cases} Q = \frac{nV_s V_o [M + (2D - 1)]^2}{16f_s L (M + 1)} & nV_s \leq V_o \\ Q = \frac{nV_s V_o [\frac{1}{M} + (2D - 1)]^2}{16f_s L (\frac{1}{M} + 1)} & nV_s > V_o. \end{cases} \quad (4)$$

The ZVS condition of DAB converter are given by

$$\begin{cases} D > \frac{1}{2} (1 - M) & nV_s \leq V_o \\ D > \frac{1}{2} (1 - \frac{1}{M}) & nV_s > V_o. \end{cases} \quad (5)$$

The ratio of the backflow power to the real power and ZVS condition are plotted in the M - D plane of Fig. 4. It should be noted that the operating point moves into the non-ZVS region with high backflow power as the load decreases. Therefore, system efficiency is significantly reduced at light-load condition for SPS of DAB converter.

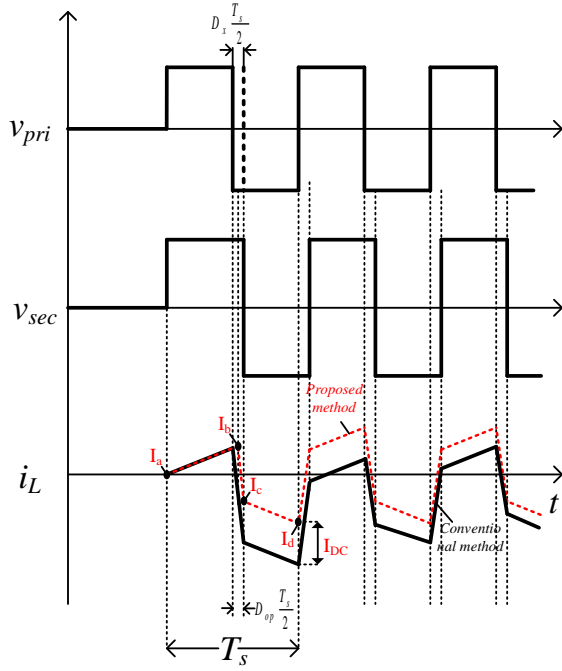


Fig. 5: DC bias elimination key waveform of the proposed burst-mode control.

III. PROPOSED BURST-MODE

A. Burst-Mode Operation

In this burst-mode operation, the PWM signal will be turned on with the burst-mode period T_b and the burst duty D_b is used as a control variable for regulating the output voltage V_o as shown in Fig. 4. When the burst-mode is applied to in DAB converter, the voltage gain can be expressed as

$$M_b = MD_b = \frac{D(1-D)T_s R_L}{2Ln^2} D_b. \quad (6)$$

It should be noted that the output voltage can be regulated by either the regular duty cycle, D or the burst-mode duty cycle, D_b as shown in Fig. 6.

To minimize the backflow power in the burst-mode, the DAB converter should be operated at the optimally calculated duty cycle D_{op} . The optimal duty cycle D_{op} for the minimum backflow power of DAB converter can be found and when backflow power in (4) is set to zero. As such, the optimal duty cycle D_{op} can be expressed as

$$\begin{cases} D_{op} = \frac{1}{2}(1 - M_b) & nV_s \leq V_o \\ D_{op} = \frac{1}{2}\left(1 - \frac{1}{M_b}\right) & nV_s > V_o. \end{cases} \quad (7)$$

While the minimum backflow power in burst-mode is achieved by D_{op} , the output voltage can be regulated by D_b . Accordingly the updated voltage gain formula M_b can be given by

$$M_b = \frac{D_{op}(1-D_{op})T_s R_L}{2Ln^2} D_b. \quad (8)$$

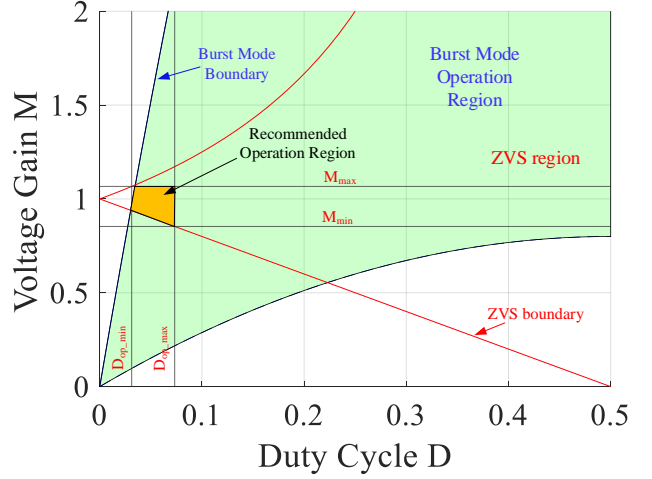


Fig. 6: Determination of the operation region for proposed burst-mode control.

B. DC Bias elimination

In the burst-mode operation, the series inductor current i_L jumps from zero to the burst-mode current. In this case, DC bias current I_{DC} occurs as shown in Fig. 5 which may cause the transformer saturation [15], [16]. To eliminate DC bias current, the additional duty cycle D_x can be added to the optimal regular duty D_{op} to cancel this effect. In the burst-mode operation, the vertex value of the series inductor current i_L can be expressed as follows: ($nV_s > V_o$)

$$\begin{aligned} I_a &= 0 \\ I_b &= I_a + \frac{nV_s - V_o}{L} (1 + D_{op}) \frac{T_s}{2} \\ I_c &= I_b + \frac{nV_s + V_o}{L} D_x \frac{T_s}{2} \\ I_d &= I_c + \frac{V_o - nV_s}{L} (1 - D_x) \frac{T_s}{2}. \end{aligned} \quad (9)$$

By arranging (9),

$$I_{DC} = (D_{op}(nV_s - V_o) + 2D_x nV_s) \frac{T_s}{2L} \quad nV_s > V_o. \quad (10)$$

To nullify I_{DC} , the value of I_d should meet the following condition:

$$I_d = \frac{-nV_s + V_o(1 - 2D_{op})}{4} \frac{T_s}{L} \quad nV_s > V_o. \quad (11)$$

By substituting (11) to (9), the value of D_x for zero bias current is given by

$$D_x = \frac{1}{4}(M - 2D_{op} - 1) \quad nV_s > V_o \quad (12)$$

In order not to disturb the optimal duty operation, the regular duty cycle is applied only for the first pulse of each burst-mode cycle, and its formula is given by

$$D'_n = D_{op} + D_x. \quad (13)$$

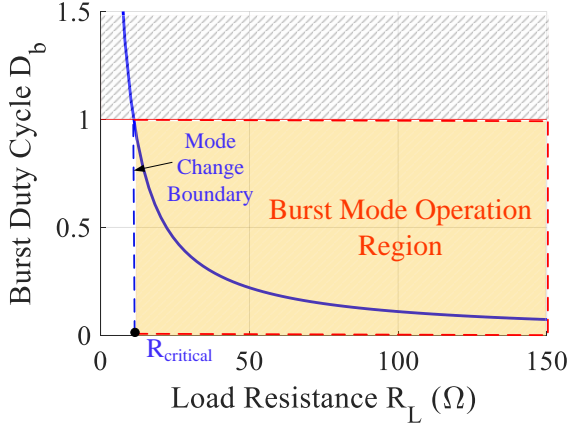


Fig. 7: Critical load value $R_{critical}$ for mode change condition.

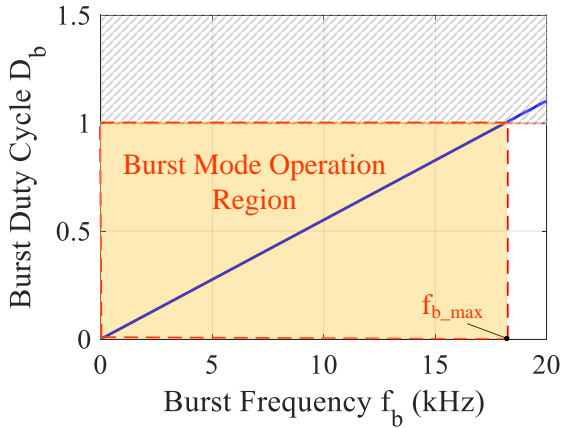


Fig. 8: The burst-mode duty cycle D_b versus burst frequency f_b .

IV. DESIGN PROCEDURE

According to the analysis of the Section II the design procedure is established in this section. From the updated voltage gain formula in (8), it can be realized that when the duty cycle D is fixed at optimal duty cycle D_{op} for the minimum backflow power, the burst duty cycle D_b should be used to regulate output voltage, and it is given by

$$D_b = \frac{2M_bLn^2}{D_{op}(1-D_{op})T_sR_L}. \quad (14)$$

The burst-mode duty cycle D_b is a function of the load resistance R_L . It is well known that the range of the burst duty cycle is $0 \leq D_b \leq 1$. Therefore, the critical load value $R_{critical}$ for the mode switching between the burst-mode and the normal mode of DAB converter is determined as shown in Fig. 7 and its formula is given by

$$R_{critical} = \frac{2M_bLn^2}{D_{op}(1-D_{op})T_s}. \quad (15)$$

By the way the output capacitor filter C_o plays very importance role in the burst-mode. Because the power is directly supplied

from C_o to load under the burst-mode, the maximum allowable output voltage ripple ΔV_{max} is directly related to capacitance value of C_o as shown

$$C_o = \frac{I_o}{\Delta V_o f_b}. \quad (16)$$

By substituting (16) into (14), the burst duty cycle D_b can be rewritten as follows:

$$D_b = \frac{2M_bLn^2}{D_{op}(1-D_{op})T_s} \frac{f_b C_o \Delta V_o}{V_o}. \quad (17)$$

It should be noted that with given the maximum allowable output voltage ripple ΔV_{max} , the higher f_b would lead to the smaller C_o . The burst-mode duty cycle D_b versus burst frequency f_b can be plotted as shown in Fig. 8. Therefore, the burst-mode frequency is also determined. The design process of the proposed burst-mode is as follows:

- 1) The initial system parameters such as V_s , V_o , P_o , f_s , f_b , and ΔV_{max} are given by the system requirement.
- 2) The voltage gain M_b and the optimal duty cycle D_{op} can be calculated by (2) and (7).
- 3) The value of inductance L can be calculated by (3).
- 4) The critical load resistance value $R_{critical}$ is calculated by (15) and (17).
- 5) Output voltage C_o is calculated by (16) then design procedure is repeated from step 4. Otherwise the design procedure is finished.

TABLE I: System parameters.

Symbol	Parameters	Values	Unit
V_s	DC input voltage	400	V
V_o	DC output voltage	100-180	V
f_s	Switching frequency	50	kHz
P_o	Output power	0-4	kW
n	Transformer turns ratio	0.5	
C_o	Output filter capacitance	500	μ F
L	Series inductance	50	μ H
f_b	Burst frequency	2.5	kHz
$R_{critical}$	Critical value of load resistance	50	Ω

V. EXPERIMENTAL VERIFICATION

To verify the proposed control strategy, a 4 kW DAB converter prototype was built as shown in Fig. 9. The design procedure in Section IV is applied to design the system parameters shown in Table I. DSP (TMS320F28335 from Texas Instruments) is used as the digital controller for algorithm implementation. MOSFET module(F4-17MR12W1M1H B76) is used for main power switches. A power analyzer (Yokogawa Electric, WT1804E) is used for efficiency measurement. Several experimental tests are conducted to verify the performance of the proposed burst-mode control, which was performed with buck type.

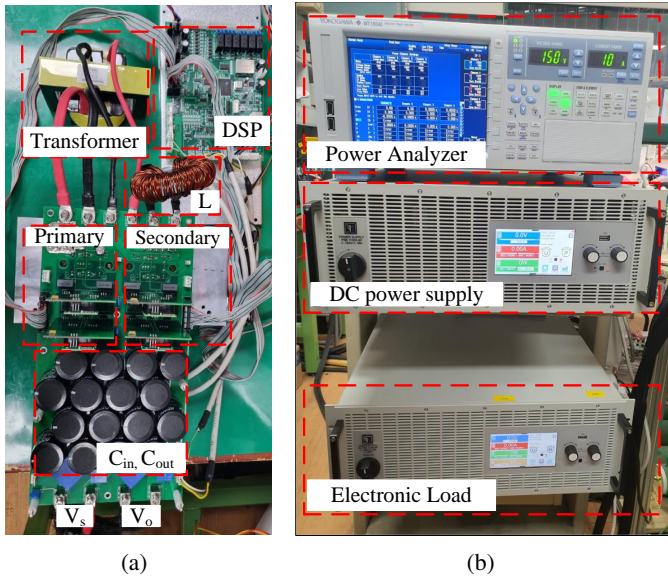


Fig. 9: Experimental setup: (a) prototype DAB converter (b) DC power supply, electronic load, and measurement equipment.

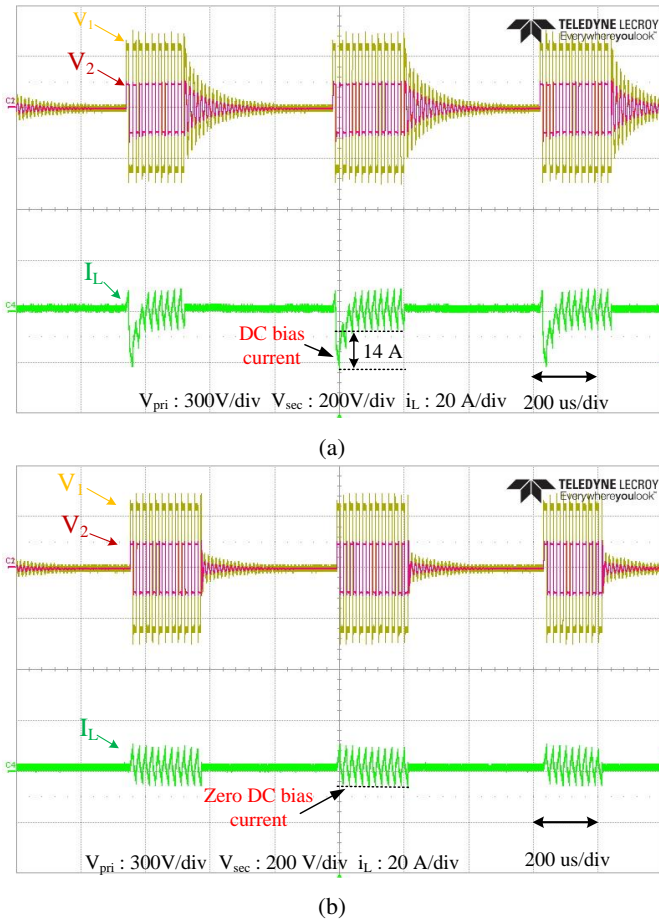


Fig. 10: Experimental waveforms of DC bias elimination (a) conventional burst-mode (b) proposed burst-mode.

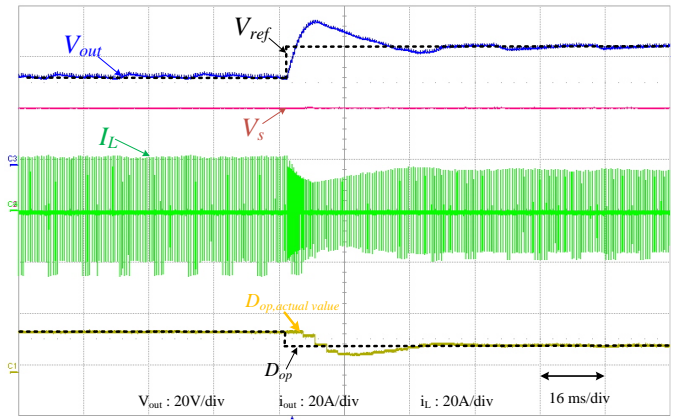


Fig. 11: Experimental waveforms of the proposed burst-mode control when V_{ref} changes from 90 V to 120 V.

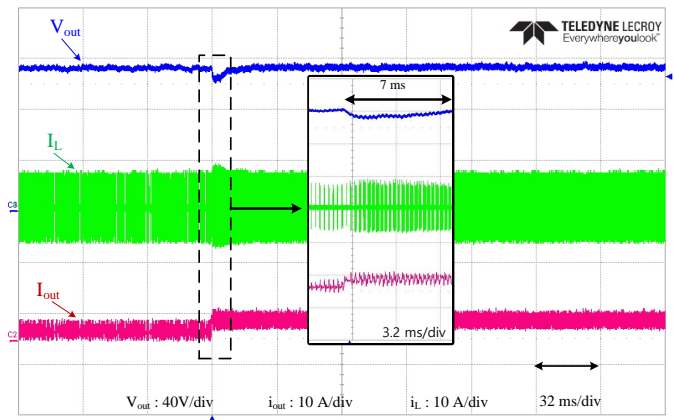


Fig. 12: Experimental waveforms of DAB converter of the proposed burst-mode control when load changes from 80 Ω to 40 Ω .

In case of the conventional burst-mode without DC bias elimination, there is 14 A DC at starting up the PWM of the burst-mode as shown in Fig. 10a. In the proposed method, after the DC bias current elimination is activated, there is zero bias current as shown in Fig. 10b.

The step change of output voltage V_o is also tested when V_{ref} steps up from 90 V to 120 V. The output voltage V_o can be regulated well with the reference value. Moreover, the optimal duty cycle D_{op} is changed from 0.275 to 0.2 when the V_o is increased from 90 V to 120 V, which matches well with calculation value in Fig. 11.

The current is increased from 1.5 A to 3 A when the load resistance is changed from 80 Ω to 40 Ω when The undershoot of the output voltage is 4 V, which is 4 % of the steady-state output voltage as shown in Fig. 12.

The mode switching operation of the proposed control strategy is tested: burst-mode to normal mode and normal mode to burst-mode. In the case of burst-mode to normal mode, the load resistance is reduced from 80 Ω to 40 Ω when the output current changes from 1.5 A to 3 A. During the mode switching the output voltage can be regulated with a

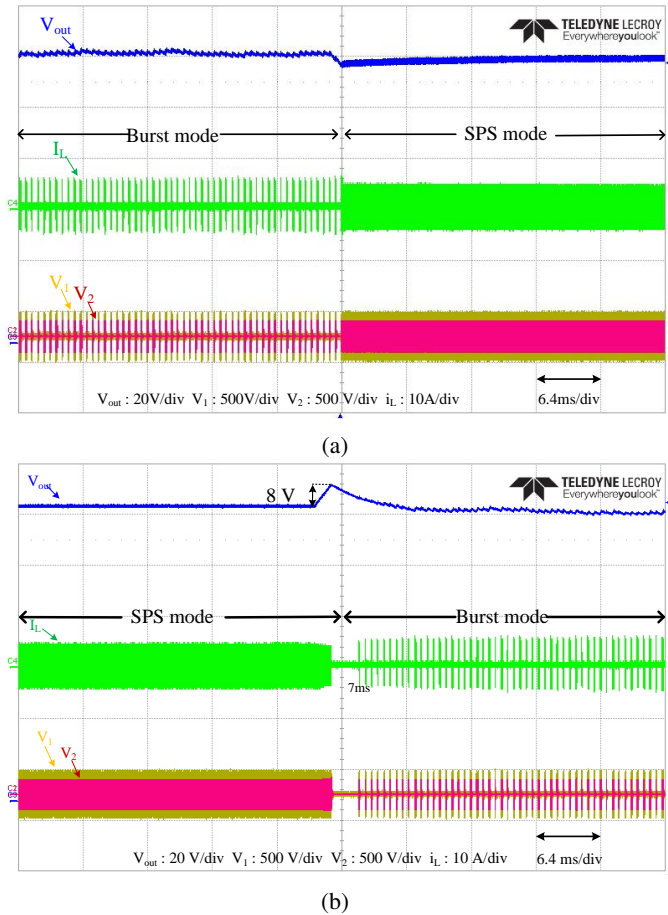


Fig. 13: Experimental waveforms of the mode switching (a) from burst-mode to normal-mode (b) from normal-mode to burst-mode.

slight undershoot as shown in Fig. 13a. Moreover, in the case from normal-mode to burst-mode, when the load resistance is increased from 40Ω to 80Ω , the output current changes from 3 A to 1.5 A . During the mode change the output voltage can be regulated with a slight overshoot as shown in Fig. 13b.

The efficiency of the proposed method is compared with conventional burst-mode as shown in Fig. 14. Due to the ZVS operation and minimum backflows power, the efficiency of the proposed method is much higher than conventional method in entire load condition.

VI. CONCLUSION

In this paper, the burst-mode for SPS-modulation DAB converter is proposed. The DAB converter is operated at minimum backflow power condition as well as ZVS at light-load condition. Therefore, the system efficiency is significantly improved. The DC bias current issue of conventional burst-mode is also mitigated in the proposed method. The detailed design procedure of DAB converter for burst-mode control is also presented. The effectiveness of proposed burst-mode is verified by experiment. System efficiency can be improved by 2% compared with the conventional burst-mode method.

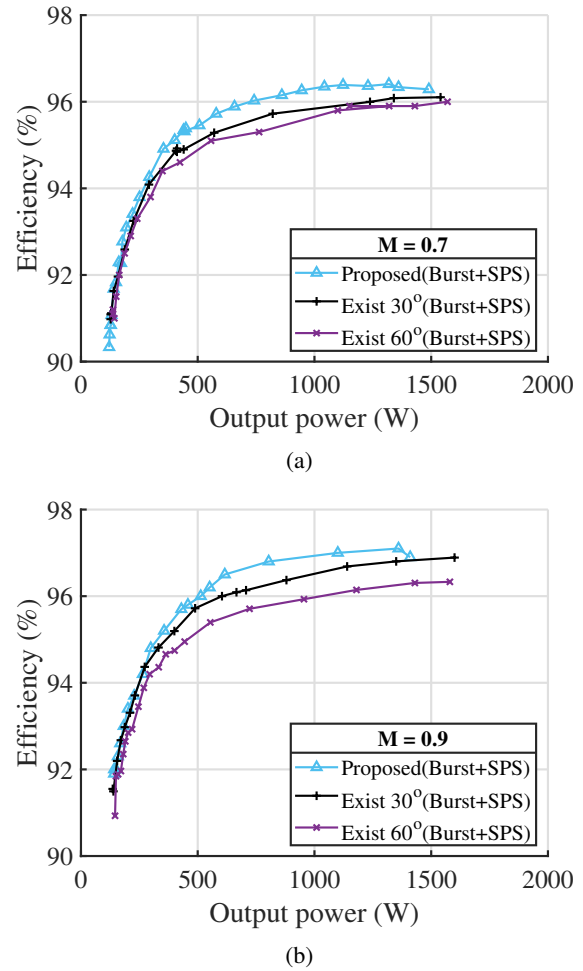


Fig. 14: Efficiency measurement comparison for a) $M = 0.7$ b) $M = 0.9$.

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